

# Lower Bounds for Algebraic Computation Trees

As part of the graduate course Algorithms and Complexity

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# Intro

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## Background-Motivation

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- Nowadays among various general methods for obtaining lower complexity bounds for this model, one of the most efficient uses homotopy invariants, Euler characteristic and Betti numbers, as arguments for the bounding functions.
- The history of this approach started probably in mid 70s with the work of Dobkin and Lipton, and features prominent results such as Ben-Or's and later Yang's.

# Main Achievements

- This paper introduces a new **topological method** for obtaining lower bounds for this general type of algorithms, formally described as algebraic computation trees
- With this method it became possible to generalize, and present **in a uniform and easy way**, almost all the known nonlinear lower bounds for algebraic computations at that time
- Able to **tackle a wide berth of previously untouchable problems** such as lower bounds for the complexity of constructions with a ruler and compass in plane Euclidean geometry.



## Example. Element Distinctness

Given  $x_1, \dots, x_n \in \mathbb{R}$ , is there a pair of indexes  $i, j$  such that

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## Theorem 1.

Any algebraic computation tree that solves the  $n$ -element distinctness problem must have complexity of at least  $\Omega(n \log n)$ .

# The Algebraic Computation Tree Model

## The Membership Problem

Let  $W \subset \mathbb{R}^n$ . Given  $x = (x_1, \dots, x_n) \in \mathbb{R}^n$  determine if  $x \in W$

# The Algebraic Computation Tree Model

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## Definition

the Algebraic Computation Tree is a binary tree  $T$  with a function that assigns:

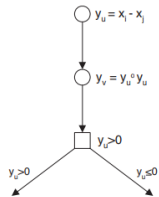
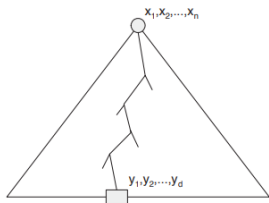
- To any leaf an output Accept or Reject
- To any vertex  $v$  with exactly one child an operational instruction of the form  $f_v := f_{v_1} \circ f_{v_2}$  or  $f_v := c \circ f_{v_1}$  or  $f_v := \sqrt{f_{v_1}}$  where  $v_i$  is a predecessor of  $v$  in  $T$ , or  $f_{v_i} \in x_1, \dots, x_n$ ,  $\circ \in \{-, +, \times, \sqrt{\quad}\}$  and  $c \in \mathbb{R}$
- To any vertex  $v$  with two children a test instruction of the form  $f_{v_1} > 0$  or  $f_{v_1} \geq 0$  or  $f_{v_1} = 0$  where  $v_1$  is a predecessor of  $v$ , or  $f_{v_i} \in x_1, \dots, x_n$

# The Algebraic Computation Tree Model

## Definitions

- We say that the computation tree  $T$  solves the membership problem for  $W$  if the answer returned is correct for every input  $x \in W$
- Let  $cost(x, T)$  denote the number of vertices that an input  $x$  passes through
- The complexity of  $T$ ,  $C(T) = \max_{x \in W} cost(x, T)$
- Let  $C(W) = \min_{T \text{ solves } W} C(T)$

# The Algebraic Computation Tree Model



# Counting Connected Components

## Definitions

Let  $V \subset \mathbb{R}^n$  be a set defined by the following polynomial equations

$$q_1(x_1, \dots, x_n) = 0, \dots, q_m(x_1, \dots, x_n) = 0$$

$$p_1(x_1, \dots, x_n) > 0, \dots, p_s(x_1, \dots, x_n) > 0 \quad (1)$$

$$p_{s+1}(x_1, \dots, x_n) \geq 0, \dots, p_h(x_1, \dots, x_n) \geq 0$$

where  $\forall i, j : p_i, q_j \in \mathbb{R}[x_1, \dots, x_n]$  and  $d = \max\{2, \deg(p_i), \deg(q_j)\}$

# Counting Connected Components

Denote by  $\#V$  the number of connected components of  $V$  has.  
For any  $n, h, d \in \mathbb{Z}$  we define

$$\beta_d(n, h) = \max\{\#V \mid V \subset \mathbb{R}^n \text{ as defined by (1)}\}$$



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Note that we do not bound the number of equations describing  $V$

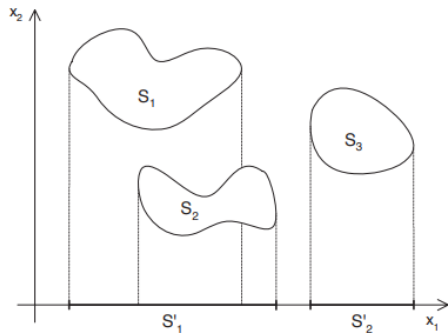
# Main Results

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# Counting Connected Components

## Theorem

For  $d \geq 2$ , 
$$\beta_d(n, h) \leq d(2d - 1)^{n+h-1}$$



## Theorem 3.

Let  $W \subset \mathbb{R}^n$  be any set, and let  $T$  be a computation tree that solves the membership problem for  $W$ . If  $N$  is the number of disjoint connected components of  $W$  and  $h = C(T)$ , then

$$2^h 3^{n+h} \geq N$$

# Main Theorem

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## Theorem 4.

For any  $W \subset \mathbb{R}^n$

$$C(W) \geq \frac{\log N}{1 + \log 3} - \frac{\log 3}{1 + \log 3} n \approx 0.38 \log N - 0.61 n$$

where  $N = \max\{\#W, \#(\mathbb{R}^n - W)\}$

# Main Theorem

## Definitions

Let  $T$  be a computation tree and let  $M(x, T)$  denote the sum of the costs of the operations along the path  $P(x)$ . The multiplicative complexity of  $T$ ,  $M(T)$ , is the maximum of  $M(x, T)$  for any  $x \in \mathbb{R}^n$ , and the (multiplicative) complexity of  $W$ ,  $M(W)$ , is the minimum  $M(T)$  for any algebraic computation tree

## Theorem 5.

For any  $W \subset \mathbb{R}^n$ ,

$$M(W) = \Omega(\log N - n)$$

where  $N = \max\{\#W, \#(\mathbb{R}^n - W)\}$

# Main Theorem

## Definitions

A  $d$ -th order decision tree  $T$  for testing if  $x \in W \subset \mathbb{R}^n$ , is a decision tree where the functions allowed are polynomials of degree at most  $d$ , each leaf of  $T$  contains the answer Accept or Reject, and for any  $x \in \mathbb{R}^n$ ,  $T$  decides correctly if  $x \in W$ . Denote by  $C_d(W)$  the minimum height for any  $d$ -th order decision tree for the set  $W$ .

## Theorem 6.

Let  $W \subset \mathbb{R}^n$  be any set, and let  $T$  be a  $d$ -th order algebraic decision tree that solves the membership problem for  $W$ . If  $N$  is the number of disjoint connected components of  $W$ , and  $h$  is the height of  $T$ , then

$$2^h \beta_d(n, h) \geq N$$

Thus for fixed  $d$ ,  $C_d(W) = \Omega(\log N - n)$

# Applications

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