

M.Sc. Program in Computer Science Department of Informatics

Algorithmic Game Theory Selfish Routing

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Selfish routing

- In mechanism design, we studied how to enforce a particular strategy (the truthful one)
- We designed the rules of the game so that being truthful was a dominant strategy of the game
- In many other settings, we cannot design a game from scratch
- But we can observe or recommend strategies
- Goal: Evaluate the equilibria of a game, as the outcomes more likely to occur

Non-atomic selfish routing

Nonatomic selfish routing

Informal description

- •Consider a directed graph depicting a network
- •Users want to send traffic from a start point to some end point
- •Each user controls an infinitesimally small quantity of traffic
- •The traffic needs to cross the edges of a path to reach the destination
- •Each edge incurs a cost (time delay, etc)
- •The cost depends on the traffic volume crossing the edge

Pigou's Example

[Pigou 1920]: One unit of traffic wants to go from s to t



Q: what will selfish network users do?

• assume everyone wants smallest-possible cost

Pigou's Example

Claim: All traffic will take the top link





Reason:

- Suppose an ε-fraction of traffic takes the bottom link
- 1-ε on the upper link
- The users on the bottom link are envious
- Only way to have an equilibrium is for everybody to take the top link
- Average delay = 1

Can We Do Better?

- We take the average delay as a metric for the network performance
- Consider instead: traffic split equally



- half of the traffic has cost ½ (much improved!)
- Average delay: $\frac{1}{2} \cdot 1 + \frac{1}{2} \cdot \frac{1}{2} = \frac{3}{4}$

Initial Network:



- Suppose again 1 unit of traffic wants to go from s to t
- Equilibrium flow: equal split
- ½ of the traffic takes the upper route
- The rest take the bottom route
- In any other split some users will have incentives to deviate

Initial Network:



Delay in each route = $\frac{1}{2}$ + 1 = 1.5 Average delay = 3/2

• Suppose the government is thinking of adding 1 very fast new road to help decrease the congestion

Initial Network:

Augmented Network:



- What will the network users do in the augmented network?
- Unique equilibrium to use the route with the fast road

Initial Network:

Augmented Network:



All traffic incurs more cost! [Braess '68]

- Formal description:
- •directed graph G = (V,E)
- source-destination pairs (s₁,t₁), ..., (s_k,t_k)
- • \mathbf{r}_i = amount of traffic that needs to go from \mathbf{s}_i to \mathbf{t}_i
 - The traffic can be split into different paths from s_i to t_i
- •for each edge e, a cost function $c_e()$
 - Assumed continuous, non-negative, and nondecreasing
 - Depends on the traffic crossing edge e
 - Usually expresses the delay of the traffic crossing edge e

Players

- Each player controls an infinitesimally small amount of flow
 - cars in a road network
 - packets in a network

Outcomes of a selfish routing game: feasible flows

- Need to specify the flow routed on every path connecting some s_i to t_i
- For an s_i - t_i path p, f_p = amount of traffic choosing p

Feasible flow vectors:

- $f_p \ge 0$, for every path p connecting some s_i to t_i
- For i=1,..., k, total flow on all s_i-t_i paths must equal the demand r_i

Consider a feasible flow f

- f can be written as a vector specifying the flow f_p for every path p connecting some s_i to t_i
- Let P_i = set of all distinct paths from s_i to t_i
- Let $P_{all} = \bigcup_i P_i$ = all the paths in the graph that are of interest to us
- f has a coordinate f_p for every $p \in P_{all}$

Representation as an edge flow vector:

- We can also write f as a vector along edges of the graph
- For every edge e, $f_e = \sum_{p: e \in p} f_p$
- We need this representation since the delay is evaluated per edge

Example:

•As a path vector we would need to specify 3 values for the 3 possible paths

•Let

- p1 be the upper path
- p2 be the bottom path
- p3 be the path using the fast link
- •A feasible flow for 1.2 units of traffic: f = (0.5, 0.3, 0.4)
- •As an edge flow vector:
 - sum in each edge e the flow that goes through e
 - E.g., for the upper rightmost edge: $f_e = 0.9$



Utility functions vs latencies

- To complete the description of the game, we need to define the utility function of a player
- Each player here is choosing a path
- It is more convenient to talk about latency/cost rather than utility
- Given a feasible flow f
 - Latency/cost on an edge e: $c_e(f_e)$ = cost experienced by the traffic going through edge e
 - Latency/cost on a path $p \in P_{all}$: $c_p(f) = \sum_{e \in p} c_e(f_e)$

Equilibrium flows

- When can we say that a flow is at equilibrium?
- When no arbitrarily small quantity of traffic can have an incentive to deviate
- Consider a feasible flow f, and a player controlling a δ amount of flow, who has chosen a path $p_1 \in P_i$
- New flow after a deviation to a path p₂:

$$f' = -\begin{cases} f_p - \delta, & \text{if } p = p_1 \\ f_p + \delta, & \text{if } p = p_2 \\ f_p, & \text{o.w.} \end{cases}$$

• Definition: A feasible flow f is a Nash equilibrium flow if for any i = 1, ..., k, any $p_1, p_2 \in P_i$, with $f_{p_1} > 0$, and $\delta \in [0, f_{p_1}]$ $c_{p_1}(f) \le c_{p_2}(f')$

Equilibrium flows

Due to continuity of the cost functions:

Equivalent definition: [Wardrop '52] A flow f is a Nash flow if for any i = 1, ..., k, and any $p_1, p_2 \in P_i$, with $f_{p1} > 0$, $c_{p1}(f) \leq c_{p2}(f)$

I.e., all flow is routed on min-cost paths [given current edge congestion]



Examples of nonequilibrium flows:



Existence

- When can we guarantee that a Nash flow exists?
- Lemma: If the cost function of every edge is continuous and non-decreasing, then the game admits a Nash flow with pure strategies
- Existence can be actually guaranteed for a wider class of congestion games (next lecture)
- Main conclusion: no matter how complex the network is, there is a way that the users can reach an equilibrium

Wardrop Equilibrium (Nash flow)

A feasible flow is a Wardrop equilibrium if for every commodity *i* :

$$\forall p, q \in P_i, f_p > 0 : c_p(f) \le c_q(f)$$

Intuitively, no player has incentive to deviate

Moreover: $\forall p, q \in P_i : f_p > 0, f_q > 0 \Rightarrow c_p(f) = c_q(f)$

Existence and Uniqueness

Let $\Phi(f) := \sum_{e \in E} \int_0^{f_e} c_e(x) dx$

Assume *f* is an equilibrium flow.

Change *f* to a feasible flow *f*' that differs with *f* in only two paths (p, q) of the same commodity: $f'_p = f_p - \delta$, $f'_q = f_q + \delta$

Existence and Uniqueness

Consider the convex program CP:

min
$$\Phi(f) := \sum_{e \in E} \int_0^{f_e} c_e(x) dx$$

so that
 $\sum_{p \in P_i} f_p = r_i, \forall i \in \{1 \dots k\}$
 $f_e = \sum_{p \in P: e \in p} f_p, \forall e \in E$
 $f_p \ge 0, \forall p \in P$

By Karush-Kuhn-Tucker optimality conditions:

A feasible flow f is optimal for CP $\begin{array}{c} & & \\ & &$

Optimal Flow

A feasible flow *f** is optimal if for every feasible flow *x*:

$$C(f^*) \le C(x)$$
 $\left(C(f) = \sum_{e \in E} f_e c_e(f_e)\right)$

Once again: $\min \sum_{e \in E} c_e(f_e) f_e$ so that $\sum_{p \in P_i} f_p = r_i, \forall i \in \{1 \dots k\}$ $f_e = \sum_{p \in P: e \in p} f_p, \forall e \in E$ $f_p \ge 0, \forall p \in P$

By KKT conditions $f^* \text{ optimal} \Leftrightarrow c_p(f^*) + \sum_{e \in p} c'_e(f^*_e) f^*_e \leq c_q(f^*) + \sum_{e \in q} c'_e(f^*_e) f^*_e,$

 $\forall i \in \{1 \dots k\}, \forall p, q \in P_i, f_p > 0$

Evaluating equilibria

- To evaluate the performance of Nash equilibria, we need to consider the derived social welfare
- Social welfare vs social cost: Since we considered the cost/latency for each user, it is more natural to consider the social cost as our performance measure: i.e., the average delay experienced in the network
- **Definition:** Given a feasible flow f, the social cost of f is

 $C(f) = \sum_{p} f_{p} c_{p}(f) = \sum_{e} f_{e} c_{e}(f_{e})$

- Theorem: All the equilibrium flows attain the same social cost
 - Follows again from the fact that cost functions are continuous and non-decreasing

Price of Anarchy in selfish routing

Q: How bad are the equilibria of a selfish routing game?

•Let f^{*} be an optimal flow (minimizing the social cost) and f be an equilibrium flow

•Given a class of selfish routing games,

 $PoA = max C(f)/C(f^*)$

- The maximization is w.r.t. all the games of the class under consideration
- E.g., how bad is PoA for arbitrary cost functions?
- For special classes of cost functions?

Price of Anarchy in selfish routing

- Let's start with linear (affine) cost functions
- Suppose that for every edge e, c_e(f_e) = a_ef_e + b_e, for some constants a_e, b_e
- Recall that the examples of Pigou and Braess fall under this class c(x)=x



- Pigou's example shows that $PoA \ge 4/3$
- Can it get worse for more complex networks?

Theorem [Roughgarden, Tardos '00]: For the class of selfish routing games with a linear cost function on each edge

PoA = 4/3

- Independent of the network topology, no matter what the graph looks like!
- Pigou's example achieves the worst-case scenario
- Main take-home message: If the cost functions are linear, selfish behavior cannot affect too much the network performance

Main ingredients of the proof for linear cost functions •Formulate the problem as a convex optimization problem

min
$$C(f) = \sum_{e \in E} f_e \cdot c_e(f_e)$$

s. t.:

$$\begin{split} \sum_{p \in P_i} f_p &= r_i, & \forall i \in \{1, 2, \dots, k\} \\ f_e &= \sum_{p: e \in p} f_p, & \forall e \in E \\ f_p &\geq 0 & \forall p \in P_{all} \end{split}$$

The analysis of the convex program shows that Lemma: A Nash flow of a given instance is an optimal flow for the instance where traffic is reduced to half ($r_i' = r_i/2$)

Main ingredients of the proof for linear cost functions

•Remaining proof relates the optimal flow with the optimal at half the traffic

•Main consequence from the proof: If every cost function is in the form $c_e = a_e f_e$ (no constant term), then PoA = 1!

• No loss in performance in this case

- Generalizing: What about non-linear cost functions?
- It is natural to assume polynomial cost functions as the next step

Description	Typical Representative	Price of Anarchy
Linear	ax + b	4/3
Quadratic	$ax^2 + bx + c$	$\frac{3\sqrt{3}}{3\sqrt{3}-2} \approx 1.6$
Cubic	$ax^3 + bx^2 + cx + d$	$\frac{4\sqrt[3]{4}}{4\sqrt[3]{4}-3} \approx 1.9$
Quartic	$ax^4 + bx^3 + cx^2 + dx + e$	$\frac{5\sqrt[4]{5}}{5\sqrt[4]{5}-4} \approx 2.2$
Degree $\leq p$	$\sum_{i=0}^{p} a_i x^i$	$\frac{(p+1)\sqrt[p]{p+1}}{(p+1)\sqrt[p]{p+1}-p} \approx \frac{p}{\ln p}$

- PoA can become unbounded as p -> ∞
- But as long as we have low degree polynomials, PoA does not grow too much

- Can we understand the worst-case scenarios under nonlinear cost functions?
- A non-linear Pigou-like network for polynomial cost functions of degree p:



Theorem (informal statement): The worst-case PoA is achieved at Pigou-like networks

Price of Anarchy (PoA)

A measure for the inefficiency of the network: $\rho(G, r, c) = PoA := \frac{C(f)}{C(f^*)}$, f an equilibrium flow and f^* an optimal flow Example: Optimal flow (OPT) and Equilirium flow (WE) Flow = $\frac{1}{2}$ C(X)=X Flow = $\frac{1}{2}$ C(X)=X Flow = $\frac{1}{2}$ Flow = 1 C(X)=1 Flow = $\frac{1}{2}$ Flow = $\frac{1}{2}$ C(X)=1 Flow = $\frac{1}{2}$ Flow = $\frac{$

Variational Inequality

Variational inequality:

fWardrop equilibrium $\Leftrightarrow \sum_{e \in E} c_e(f_e) f_e \leq \sum_{e \in E} c_e(f_e) f_e^*, \forall f^*$ feasible

• The \leftarrow part: consider *f** differing from *f* in two "same commodity" paths by $\delta > 0$ units (for all commodities).

$$\sum_{e \in E} c_e(f_e) f_e \le \sum_{e \in E} c_e(f_e) f_e^* \Rightarrow \sum_{e \in p} c_e(f_e) \Big(f_e - (f_e - \delta) \Big) \le \sum_{e \in q} c_e(f_e) \Big((f_e + \delta) - f_e \Big)$$

• The \Rightarrow part: same commodity "nonzero" paths are the cheapest of the commodity *i* and cost equal (say $c_i(f)$). Thus

$$\sum_{i} \sum_{p \in P_i} c_p(f) f_p = \sum_{i} c_i(f) \sum_{p \in P_i} f_p = \sum_{i} c_i(f) \sum_{p \in P_i} f_p^* = \sum_{i} \sum_{p \in P_i} c_i(f) f_p^* \le \sum_{p \in P} c_p(f) f_p^*$$
$$\sum_{p \in P} c_p(f) f_p \le \sum_{p \in P} c_p(f) f_p^* \Rightarrow \sum_{e \in E} c_e(f_e) f_e \le \sum_{e \in E} c_e(f_e) f_e^*$$

Bounding the PoA

Let *f* be an equilibrium flow and *f*^{*} an optimal:

$$C(f) = \sum_{e \in E} c_e(f_e) f_e \le \sum_{e \in E} c_e(f_e) f_e^* = \sum_{e \in E} \left(c_e(f_e) f_e^* + c_e(f_e^*) f_e^* - c_e(f_e^*) f_e^* \right) \Rightarrow$$

$$C(f) \leq \sum_{e \in E} c_e(f_e^*) f_e^* + \sum_{e \in E} \left(c_e(f_e) - c_e(f_e^*) \right) f_e^* = C(f^*) + \sum_{e \in E} \left(c_e(f_e) - c_e(f_e^*) \right) f_e^*$$

We bound the last term:
$$f_e^* \left(c_e(f_e) - c_e(f_e^*) \right) \leq v(f_e, c_e) f_e c_e(f_e), \quad v(u, c_e) = \frac{1}{u c_e(u)} max_{x \geq 0} \{ x(c_e(u) - c_e(x)) \}$$

Let $v(c_e) = \sup_{u \ge 0} v(u, c_e)$ and $v(D) = \sup_{c_e} v(c_e)$ where D is the family of the cost functions. We get $\sum_{e \in E} (c_e(f_e) - c_e(f_e^*)) f_e^* \le v(D) \sum_{e \in E} c_e(f_e) f_e \Rightarrow C(f) \le \frac{1}{1 - v(D)} C(f^*)$

Tightness

Assume that *u* units are to be routed from *s* to *t*.

At WE everybody goes up OPT minimizes: kc(k) + (u - k)c(u) Flow = k c(x)s tFlow = u-k c(u)

$$PoA = \frac{uc(u)}{\min_{k \in [0,v]} \left[(u-k)c(u) + kc(k) \right]} = \max_{k \in [0,v]} \left((1-k) + k\frac{c(k)}{uc(u)} \right)^{-1} = \left[1 - \max_{k \in [0,v]} k \left(\frac{c(u) - c(k)}{uc(u)} \right) \right]^{-1}$$

Previous slide:
$$PoA \leq \left(1 - \sup_{c_e \in D, u \geq 0} \max_{x \geq 0} \frac{\{x(c_e(u) - c_e(x))\}}{uc_e(u)}\right)^{-1}$$

Special cases

- For linear latency functions: $v(D) = \frac{1}{4}$ and $PoA \le \frac{4}{3}$
- For polynomial of degree *d* latency functions:

$$v(D) = \frac{d}{(d+1)^{(d+1)/d}}$$
 and $PoA \le \left(1 - \frac{d}{(d+1)^{(d+1)/d}}\right)^{-1}$

1 unit is to be routed. At WE everybody goes up For $c(x) = x^d$ OPT minimizes: $k \cdot k^{d} + (1 - k)$

