Communication Complexity

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2 Lower Bound Methods

- 3 Multiparty Communication Complexity
 - 4 Non-Determinism
- 5 Randomization









How "much" communication do we need to perform a computational task for which information is distributed among different entities?

- Simple enough so we can prove lower bounds, general enough so we can obtain important applications of these lower bounds.
- Some applications:
 - Lower bounds for Data Structures
 - Lower bounds for parallel and VLSI computations
 - Auctions (cost for prefenences)
 - Polyhedral Theory
 - Time-space tradeoff for Turing Machines

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• Two parties (Alice and Bob) with unlimited computational power

- Each holds an *n*-bit input *x*, *y*
- They want to compute f(x, y) where $f : \{0, 1\}^n \times \{0, 1\}^n \rightarrow \{0, 1\}$ is known to both.
- They have agreed upon a *protocol* of communication *P*.

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f(x, y):the parity of all bits in x, yIt holds that C(f) = 2!

- $C(f) \ge 2$ because f depends on both x and y
- C(f) ≤ 2 because there is a protocol P with COST(P) = 2 (Alice sends the parity of x and Bob XORs it with the parity of y)

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- 2 Lower Bound Methods

Observation: If the communication pattern is the same for (x, x) and (x', x') then the output of the protocol is the same for all (x, x), (x, x'), (x', x), (x', x').

- Say there is a protocol P with $COST(P) \le n-1$.
- Then there are at most 2^{n-1} communication patterns.
- But there are 2^n input pairs of the form (x, x).
- There exist two distinct pairs with the same communication pattern.

Fooling Set S

•
$$\forall (x, y) \in S : f(x, y) = b$$

• $\forall (x, y'), (x', y) \in S : f(x, y') \neq borf(x', y) \neq b$

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If f has a size-M fooling set then $C(f) \leq \log M$

Lydia Zakynthinou (NTUA)

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- M(f) the matrix of f
- Is partitioned into rectangles depending on the protocol bits (that turn out to be monochromatic why?)
- $\chi(f)$ is the minimum number of rectangles in any monochromatic tiling

Theorem (AUY'83)

 $\log \chi(f) \leq \mathcal{C}(f) \leq 16 (\log \chi(f))^2$

The rank of a matrix, rank(M), can be expressed as the minimum I s.t.:

$$M = \sum_{i=1}^{l} B_i$$
, where $rank(B_i) = 1$

Theorem

For every function f, $\chi(f) \ge \operatorname{rank}(M(f))$

Discrepancy of M(f): $Disc(f) = \max \frac{1}{2(2n)} \left| \sum_{x \in A, y \in B} M_{x,y} \right|$ over all rectangles $A \times B$

Theorem

 $\chi(f) \geq \frac{1}{\textit{Disc}(f)}$

Theorem (Eigenvalue Bound)

 $Disc(A \times B) \leq \frac{1}{2^{2n}} \lambda_{max}(M) \sqrt{|A||B|}$

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- The tiling argument is the strongest lower bound
- $\log \chi(f)$ fully characterizes C(f) within a constant factor
- The rank and fooling set methods are incomparable

Conjecture (log rank conjecture): There is a constant c > 1 such that $C(f) = O(\log(rank(M(f)))^c)$ for all f and input sizes n.

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3 Multiparty Communication Complexity

Most interesting model: "Number on the forehead"

Example: $C_3(f) = 3$ where $f(x_1, x_2, x_3) = \bigoplus maj(x_{1i}, x_{2i}, x_{3i})$ Best known lower bound for the communication complexity of an explicit function (GIP) is of the form $n/2^{-\Omega(k)}$

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Non-Determinism



- In a non-deterministic protocol P, the players are both provided an additional input z of some length m that may depend on x, y. We require that f(x, y) = 1 iff there exists z that makes the players output 1.
- COST(P) = |z|+number of bits communicated
- Inequality and Intersection are in NP.



Lower Bound Methods

3 Multiparty Communication Complexity

4 Non-Determinism





Bibliography

- All players have access to a random string *r* and we define *R*(*f*) to be the expected number of bits communicated by the protocol.
- For example, Equality has a randomized protocol with $O(\log n)$ complexity.



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7 Bibliography

$$P^{CC} = (NP^{CC} \cap coNP^{CC}) \subset BPP^{CC}$$

- P^{CC}: deterministic polylog time
- *RP^{CC}*: *polylog* time error at "no" instances only at most 1/4 (1-sided error)
- BPP^{CC}: polylog time correct with probability 3/4 (2-sided error)
- NP^{CC}: non-deterministic polylog time



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Thank you!

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