

Belief Revision and Dynamic Doxastic Logic

Konstantakatos Vangelis

National Technical University of Athens

Outline

Possible World Semantics for Belief Revision

Paradoxes of Introspective Belief Revision

Dynamic Doxastic Logic

References

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- ▶ A proposition is a set of possible worlds.
- ▶ There is a one to one correspondence between belief sets and propositions.
- ▶ Each belief set can be represented by the proposition that consists of those possible worlds that contain the belief set in question.

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- ▶ If \mathcal{K} is a belief set $\bigcap[\mathcal{K}] = \mathcal{K}$
- ▶ It is assumed that $\bigcap \emptyset = \mathcal{K}_\perp$
- ▶ It is convenient to represent sets of possible worlds as geometrical surfaces.

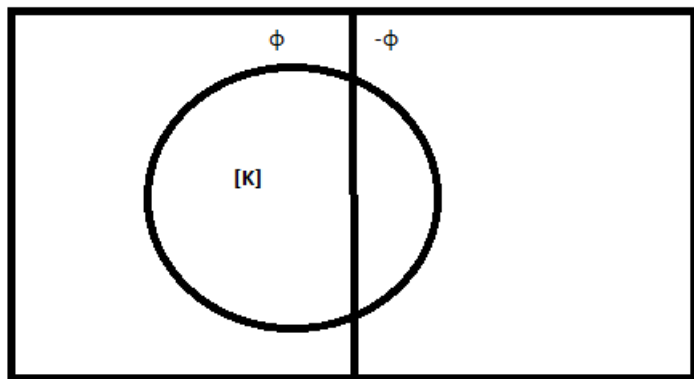
Expansion

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- ▶ Intuitively when expanding, we want to restrict the worlds that we consider possible.

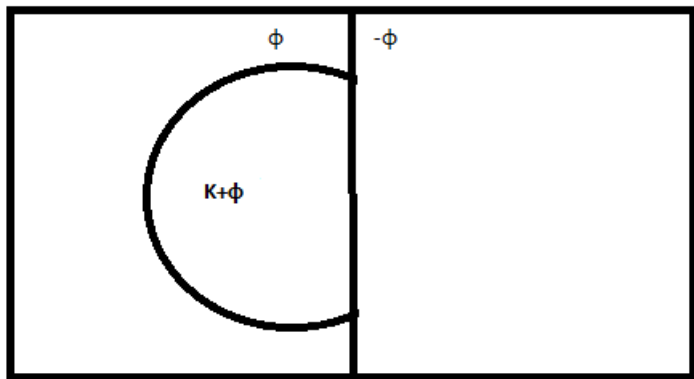
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- ▶ To expand by ϕ , simply remove all worlds that do not contain ϕ from \mathcal{K} .

Expansion



Expansion



Contraction

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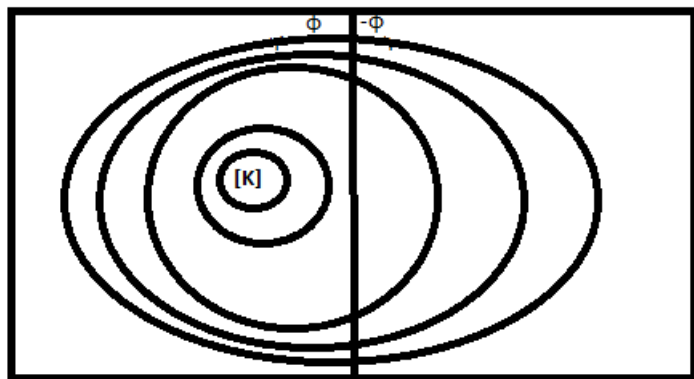
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- ▶ The intuition for contraction with ϕ tells us we should add some worlds that contain $\neg\phi$.
- ▶ But which ones?

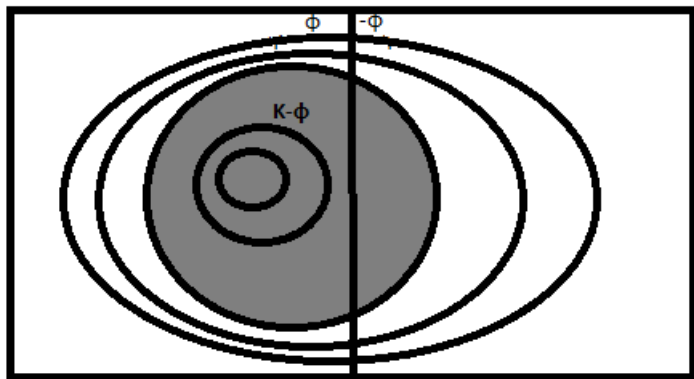
Contraction

- ▶ The intuition for contraction with ϕ tells us we should add some worlds that contain $\neg\phi$.
- ▶ But which ones?
- ▶ The equivalent for entrenchment here, is what is called a system of spheres.
- ▶ Intuitively, we have spheres surrounding $[\mathcal{K}]$, and when we have to give up some of our beliefs, we fall back to the closest sphere that we can.

Contraction



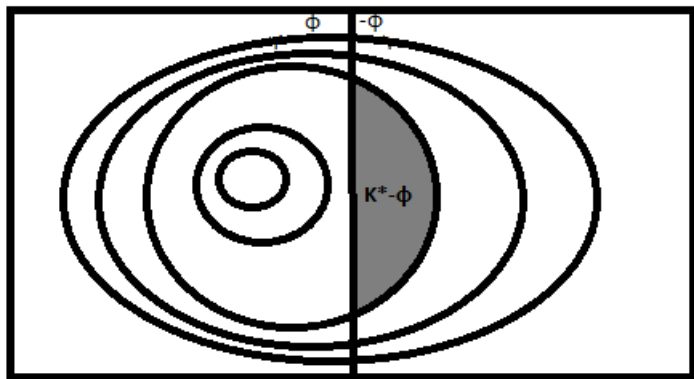
Contraction



Revision

Revision can be easily defined in the same way. In the following figure we show revision of \mathcal{K} with $\neg\phi$.

Revision



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Theorem 1

Sphere based contraction corresponds exactly to transitively relational partial meet contraction.

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- ▶ A straightforward way would be to translate $\phi \in \mathcal{K}$ to $K\phi$ or $B\phi$.
- ▶ Gaining new beliefs should correspond to eliminating access to worlds.
- ▶ Giving up beliefs should allow the agent to consider worlds possible that were previously inaccessible.

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- ▶ Note that $M, (2, 1) \models \phi$ and $\neg\phi \notin \mathcal{K}^a$.
- ▶ Now suppose that someone publicly announces ϕ .
- ▶ This means that A can rule out (0,1) and conclude that $\neg\phi$.
- ▶ A after revising with ϕ , will have $\neg\phi \in \mathcal{K}^a \circledast \phi$, therefore violating postulate *success*.

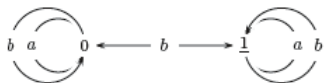
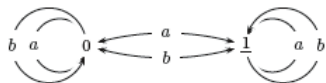
Effect on Third Parties

- ▶ Assume again two S5 agents A,B, and only 2 possible worlds, one where p is true, and one where $\neg p$ is true. The actual world is the one where p .
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- ▶ Assume also that it is common knowledge that neither A nor B know whether p
- ▶ Suppose that A learns that in fact p .
- ▶ A revises with p . But now B also learns something. He learns that A know whether p !

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- ▶ This not absurd , but it seems suspicious that B learns something when we only specified that A revises with p .
- ▶ We need a language that states explicitly what kind of event made A change her mind, and therefore making precise what b notices about this.

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- ▶ We end up with \mathcal{K}_\perp just by revising a consistent belief set with a consistent formula!

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- ▶ By negative introspection we have $\neg B\phi, \neg B\neg\phi \in \mathcal{K}$
- ▶ What would happen if our agent were to learn ϕ ?
- ▶ By the *success* postulate and positive introspection we have $B\phi \in \mathcal{K} \circledast \phi$, and by *preservation* we have that $\neg B\phi \in \mathcal{K} \circledast \phi$, giving us again the inconsistent belief set!

Static Belief Sets

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- ▶ By positive introspection, we have $B\phi \in \mathcal{K}_2$ and by negative introspection we have $\neg B\phi \in \mathcal{K}_1$.
- ▶ Since $\mathcal{K}_1 \subset \mathcal{K}_2$, $\neg B\phi \in \mathcal{K}_2$. \mathcal{K}_2 is inconsistent!
- ▶ This even violates axiom D.

Dynamic Doxastic Logic

Seegerberg

“AGM is not really logic, it’s a theory about theories.”

Dynamic Doxastic Logic

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- ▶ DDL is a modal logic where you can explicitly express the belief revision operations, as well as beliefs about beliefs in the object language.
- ▶ Bp is a formula in DDL, while $p \in \mathcal{K}$ of AGM is not in the same language as p .
- ▶ $B\neg Bp$ can be expressed in DDL, while $((p \notin \mathcal{K}) \in \mathcal{K})$ is not well formed in AGM.
- ▶ Operators $[\oplus]$, $[\ominus]$, $[\odot]$ with the intended reading of for instance $[\oplus\phi]\psi$, after expansion with ϕ , ψ holds.

Dynamic Doxastic Logic

Definition 2

$\phi := p \mid \neg\phi \mid \phi \wedge \phi \mid B_a\phi \mid [\alpha]\phi$

$\alpha := \oplus_a\phi \mid \ominus_a\phi \mid \otimes_a\phi$

- ▶ In this language a postulate like success for revision becomes simply $[\otimes_a\phi]\phi$.
- ▶ We can even express interesting properties such as: Although i believes that ϕ and ψ are equivalent, he does not believe that j revision with either of them has the same effect.
- ▶ $B_i((\phi \leftrightarrow \psi) \wedge [\otimes_j\phi]B_j\chi \wedge [\otimes_j\psi]\neg B_j\chi)$

Dynamic Doxastic Logic

- ▶ If we want to stay close to the AGM postulates we will have to restrict our language.

Definition 3

$$\phi_0 := \phi \mid \neg\phi_0 \mid \phi_0 \wedge \phi_0$$

$$\phi := \phi_0 \mid \neg\phi \mid \phi \wedge \phi \mid B\phi_0 \mid [\oplus\phi_0]\phi \mid [\ominus\phi_0]\phi$$

- ▶ We assume that all the modal operators are normal modal operators(they satisfy Necessitation and Modus Ponens), and we also assume that $[\oplus]$, $[\ominus]$ have the properties of objective persistence, functionality and idempotence.

Dynamic Doxastic Logic

$$\psi \leftrightarrow [\odot\phi]\psi$$

$$\langle \odot\phi \rangle \psi \rightarrow [\odot\phi]\psi$$

$$[\odot\phi] \rightarrow [\odot\phi][\odot\phi]\psi$$

objective persistence

partial functionality

idempotence

Doxastic Dynamic Logic

Some of the AGM postulates in this language are give below:

1. $\vdash \phi \leftrightarrow \psi \implies \vdash [\odot\phi]\chi \leftrightarrow [\odot\psi]\chi$ *congruence*
2. $B\phi \rightarrow (\chi \leftrightarrow [\oplus\phi]\chi)$ *modal($\mathcal{K} \oplus 4$)*
3. $[\oplus\phi]B\psi \leftrightarrow B(\phi \rightarrow \psi)$ *Ramsey Expansion*
4. $[\ominus\phi]B\chi \rightarrow B\chi$ *modal($\mathcal{K} \ominus 2$)*
5. $B\phi \rightarrow (B\chi \rightarrow [\ominus\phi][\oplus\phi]\chi)$ *modal recovery*

Dynamic Doxastic Logic

Leitgeb and Segerberg(2007)

“We predict that the two research programmes of DDL and DEL will merge in the long run into the single logical endeavor of DBC:Dynamic Logics of Belief Change.”

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