### Action Models

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#### Dynamic Epistemic Logic: Action Models,

#### by van Ditmarsch, Hans, van der Hoek, Wiebe, Kooi, Barteld

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### Syntax

Semantics

### Contents

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- First Basic Example
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### 2 Action Model Logic

#### Public Announcements

Convey the same information for all agents

- Restriction of the model
- Restriction of the accessibility relations

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- Restriction of the model
- Restriction of the accessibility relations

#### **Epistemic Actions**

Convey different information to different agents Refinement of accessibility relations



## Basic Example

#### Buy or Sell?

Two stockbrokers Anne and Bill, having a little break in a Wall Street bar, sitting at a table. A messenger comes in and delivers a letter to Anne. On the envelope is written "urgently requested data on United Agents". Anne opens and reads the letter in the presence of Bill.

(United Agents is doing well.)

Modelled as an epistemic state, with agents Anne ( $\alpha$ ) and Bill (b):

- Atom *p*: United Agents is doing well
- Atom  $\neg p$ : United Agents is not doing well

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 $(\mathsf{Read},\mathsf{p})$ 

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### $(\mathsf{Read},\mathsf{p})$

An example of a valid formula in this model is

 $C_{\alpha,b}(K_{\alpha}p \vee K_{\alpha} \neg p)$ 

Symbolising the state transition induced by action (Read,p) as:

$$0 - a, b - \underline{1} \xrightarrow{(\mathsf{Read}, \mathsf{p})} 0 - \underline{b} - \underline{1}$$

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Actually there are two possible actions, **p** and **np**.

- Action **p** has precondition atom p,  $pre(\mathbf{p}) = p$
- Action **np** has precondition atom  $\neg p$ , pre(**np**) =  $\neg p$

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So action model (Read,p) is symbolised as:

The partition of possible actions  $\{p,np\}$  for our agents is:

- Anne:  $\{p\}$ ,  $\{np\}$
- Bill: {**p**,**np**}

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Anne can distinguish two actions, she can also distinguish the results from those actions, this is called *perfect recall*. Bill cannot.

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 $(0, \mathbf{np}) \sim_{b} (1, \mathbf{p})$  are the same for Bill



Two states are indistinguishable for an agent if and only if they resulted from two indistinguishable actions executed in two already indistinguishable states.



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We allow (s, s) pairs such that s can be executed in s

$$M, s \models \mathsf{pre}(s)$$

### Construction as a Restricted Modal Product

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A modal product of two modal structures is formed by taking the Cartesian product of their domains.

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#### Restricted Modal Product

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### Basic Example Analysis (as modal product)

In the case of the model (*Letter*, 1) and the action model (**Read**, **p**), the result of computing the restricted modal product is:



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Action Model Logic

### Syntactic or Semantic objects?

Let's consider the action model (Read,p).



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Action Model Logic

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#### Syntactic Object

The preconditions of these 'domain' objects are formulas, so the action model therefore is nothing but some operator with these formulas as arguments, that constructs a more complex formula.

## Action Models as Syntactic Objects

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  - not the action models themselves are named, but the frames underlying them
- Enumerating frames, inductively
  - A countable supply of elements of the domain (action points)
  - Finite set of agents.
  - Set of pointed frames is enumerable, so the set of names for such frames is also enumerable

## Action Models as Semantic Objects

- Replace the preconditions of action points, with semantic propositions
- Semantic proposition  $\llbracket \phi \rrbracket_M$  stands for  $\{s \in \mathcal{D}(M) | M, s \models \phi\}$ , where  $\llbracket \phi \rrbracket$  can be seen as:
  - function from epistemic models to subsets of their domains
  - function from epistemic states to  $\{0,1\}$
- $\blacksquare$  Propositions  $[\![\phi]\!]$  are inductively defined
- [pre] will be the semantic precondition function

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Exapmle: In action model (Read,p), we will write [pre](p) = [p]



#### 1 Introduction

- 2 Action Model Logic
  - Syntax
  - Semantics

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## Action Model

#### Action Model

Let  $\mathcal{L}$  be any logical language for given parameters agents A and atoms P. An S5 action model M is a structure  $(S, \sim, pre)$  such that:

- S is a domain of action points
- $\blacksquare$  for each  $\alpha \in A, \sim_{\alpha}$  is an equivalence relation on S
- pre : S  $\rightarrow \mathcal{L}$  is a preconditions function that assigns a precondition pre(s)  $\in \mathcal{L}$  to each s  $\in$  S

A pointed S5 action model is a structure (M, s) with  $s \in S$ .

Svntax

## Syntax of Action Model Logic

#### Language of action model logic

Given agents A and atoms P. The language of action model logic  $\mathcal{L}_{KC\otimes}(A, P)$  is the union of the formulas  $\varphi \in \mathcal{L}_{KC\otimes}^{stat}(A, P)$  and the actions  $\alpha \in \mathcal{L}_{KC\otimes}^{act}(A, P)$  defined by: Svntax

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where  $p \in P$ ,  $\alpha \in A$ ,  $B \subseteq A$ , and (M,s) a pointed action model

- with a finite domain S, and
- s.t. for all  $t \in S$ , the precondition pre(t) is a  $\mathcal{L}_{KC\otimes}^{stat}(A, P)$ -formula that has already been constructed.

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Note,  $\langle \alpha \rangle \varphi$  is defined as  $\neg [\alpha] \neg \varphi$ .

Syntax



Given agents A and atoms P.

Skip

Epistemic action skip is defined as



Syntax



Given agents A and atoms P.

#### Skip

Epistemic action *skip* is defined as ( $\langle \{s\}, \sim, \text{pre} \rangle, s$ ), with  $\text{pre}(s) = \top$ , and  $s \sim_{\alpha} s$  for all  $\alpha \in A$ .



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#### Public announcement

# The action model $pub(\varphi)$ , that stands for the truthful public announcement of $\varphi$ , is defined as



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#### Exercise 1

Show that epistemic action (Read, p) from the basic example is a well-formed epistemic action in the language  $\mathcal{L}_{KC\otimes}^{act}(\{\alpha, b\}, \{p\})$ 

# Composition

#### Composition of action models

Let  $M = \langle S, \sim, pre \rangle$  and  $M' = \langle S', \sim', pre' \rangle$  be two action models in  $\mathcal{L}^{act}_{KC\otimes}(A, P)$ . Then their composition (M; M') is the action model  $\langle S'', \sim'', pre'' \rangle$  such that:

• 5 = 5 × 5  
• (s,s') 
$$\sim''_{\alpha}$$
 (t,t') iff s  $\sim_{\alpha}$  t and s'  $\sim'_{\alpha}$  t'

• 
$$pre''((s,s')) = \langle M, s \rangle pre'(s')$$

# Semantics of Action Model Logic

#### Semantics of formulas and actions

Given are epistemic state (M, s) with  $M = \langle S, \sim, V \rangle$ , action model  $\mathsf{M} = \langle \mathsf{S}, \sim, \mathsf{pre} \rangle$ , and  $\varphi \in \mathcal{L}^{stat}_{\kappa C \otimes}(A, P)$  and  $\alpha \in \mathcal{L}^{act}_{\kappa C \otimes}(A, P)$ . iff  $s \in V_p$  $M, s \models p$  $M, s \models \neg \varphi$  iff  $M, s \not\models \varphi$  $M, s \models \varphi \land \psi$  iff  $M, s \models \varphi$  and  $M, s \models \psi$  $M, s \models K_{\alpha} \varphi$  iff for all  $s' \in S$  :  $s \sim_{\alpha} s'$  implies  $M, s' \models \varphi$  $M, s \models C_B \varphi$  iff for all  $s' \in S$  :  $s \sim_B s'$  implies  $M, s' \models \varphi$ iff for all  $M', s' : (M, s) \llbracket \alpha \rrbracket (M', s')$  $M, s \models [\alpha] \varphi$ implies  $M', s' \models \varphi$ (M, s) [M, s] (M', s') iff  $M, s \models pre(s)$  and  $(M', s') = (M \otimes M, (s, s))$  $\llbracket \alpha \cup \alpha' \rrbracket = \llbracket \alpha \rrbracket \cup \llbracket \alpha' \rrbracket$ 

# Semantics of Action Model Logic

#### Restricted Modal Product

 $M' = (M \otimes M)$  is a restricted modal product of an epistemic model and an action model, defined as  $M' = \langle S', \sim', V' \rangle$  with:

• 
$$S' = \{(s,s) \mid s \in S, s \in S \text{ and } M, s \models pre(s)\}$$

• 
$$(s,s) \sim'_{\alpha} (t,t)$$
 iff  $s \sim_{\alpha} t$  and  $s \sim_{\alpha} t$ 

• 
$$(s,s) \in V'_p$$
 iff  $s \in V_p$ 

# Semantics of Action Model Logic

#### Restricted Modal Product

 $\begin{aligned} &M' = (M \otimes \mathsf{M}) \text{ is a restricted modal product of an epistemic model} \\ &\text{and an action model, defined as } M' = \langle S', \sim', V' \rangle \text{ with:} \\ & \quad \mathsf{S}' = \{(s, \mathsf{s}) \mid s \in S, \mathsf{s} \in \mathsf{S} \text{ and } M, s \models \mathsf{pre}(\mathsf{s})\} \\ & \quad \mathsf{s}(s, \mathsf{s}) \sim'_{\alpha}(t, \mathsf{t}) \text{ iff } s \sim_{\alpha} t \text{ and } \mathsf{s} \sim_{\alpha} \mathsf{t} \\ & \quad \mathsf{s}(\mathsf{s}, \mathsf{s}) \in V'_{\rho} \text{ iff } s \in V_{\rho} \end{aligned}$ 

The set of valid formulas from  $\mathcal{L}_{KC\otimes}^{stat}$  without common knowledge under the above semantics will be denoted the *action model validities*, or *AM*. The set of validities from the full language  $\mathcal{L}_{KC\otimes}^{stat}$  is *AMC*.

# Semantics of Action Model Logic

# Note $M, s \models \langle \alpha \rangle \varphi$ iffthere is a $M', s' : (M, s) \llbracket \alpha \rrbracket (M', s')$ <br/>and $M', s' \models \varphi$

# Semantics of Action Model Logic

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#### Specifically:

 $M, t \models \langle M, s \rangle \operatorname{pre}'(s')$  iff  $M, t \models \operatorname{pre}(s) \land [M, s] \operatorname{pre}'(s')$ 



# Some Propositions

#### Proposition 1

Let  $(M, s), (M', s') \in \mathcal{L}_{KC\otimes}^{act}(A, P)$ , and  $\varphi \in \mathcal{L}_{KC\otimes}^{stat}(A, P)$ . Then  $[(M, s); (M', s')]\varphi$  is equivalent to  $[M, s][M', s']\varphi$ .



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#### Proposition 2

Let 
$$\alpha, \beta, \gamma \in \mathcal{L}_{KC\otimes}^{act}(A, P)$$
, then:  
•  $((\alpha \cup \beta); \gamma)$  equals  $((\alpha; \gamma) \cup (\beta; \gamma))$   
•  $(\alpha; (\beta \cup \gamma))$  equals  $((\alpha; \beta) \cup (\alpha; \gamma))$ 

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#### **Proposition 3**

Let  $\alpha, \beta \in \mathcal{L}_{KC\otimes}^{act}(A, P)$ . Then  $[\alpha \cup \beta]\varphi$  is equivalent to  $[\alpha]\varphi \wedge [\beta]\varphi$ .

# A Corollary and Exercises

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All expressions  $[\alpha]\varphi$  are equivalent to some conjunction  $\bigwedge [M, s]\varphi$ .

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#### Exercise 2 (crash, skip)

Show the following (assume given set of agents A and atoms P): •  $\varphi \rightarrow [\text{skip}]\varphi$  is valid •  $[\text{crash}]\perp$  is valid

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Show the following (assume given set of agents A and atoms P):

- $\varphi \rightarrow [\text{skip}]\varphi$  is valid
- $[crash] \perp$  is valid

#### Exercise 3 (Action model for mayread)

Give an action model for the epistemic action **mayread**, where Bill considers it possible that Anne may have read the letter, and where, actually, she doesn't.

# Some More Exercises

#### Exercise 4 (Action model for **bothmayread**)

Give an action model for the epistemic action **bothmayread**, where both Anne and Bill consider it possible that the other may have read the letter, and where, actually, both read the letter.

# Some More Exercises

#### Exercise 4 (Action model for **bothmayread**)

Give an action model for the epistemic action **bothmayread**, where both Anne and Bill consider it possible that the other may have read the letter, and where, actually, both read the letter.

#### Exercise 5 (Action composition)

Given the epistemic state (Letter, 1) where both Anne and Bill do not know p, and where p is true, first Anne reads the letter (Read<sub> $\alpha$ </sub>, p $\alpha$ ) and then Bill reads the letter (Read<sub>b</sub>, pb). Compute the composition of Read<sub> $\alpha$ </sub> and Read<sub>b</sub>.

# Limitations of finite models

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Example: The 'epistemic riddle' concerning consecutive numbers.