

Second-Order Logic and Fagin's Theorem

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Περιεχόμενα

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Second Order Logic

Definition

Second-Order Logic extends first order logic with quantification over relations.

$$\exists X\phi,$$

where X has arity m .

$\exists X\phi$ is true in a structure A if, and only if, A can be expanded by an m -ary relation interpreting X to satisfy ϕ .

$SO\exists$ and $SO\forall$

Definition

- *Existential second-order ($SO\exists$) is defined as the restriction of SO that consists of the formula of the form*

$$\exists X_1 \dots \exists X_n \phi$$

where ϕ is a first-order formula.

$SO\exists$ and $SO\forall$

Definition

- *Existential second-order ($SO\exists$) is defined as the restriction of SO that consists of the formula of the form*

$$\exists X_1 \dots \exists X_n \phi$$

where ϕ is a first-order formula.

- *Universal second-order ($SO\forall$) is defined as the restriction of SO that consists of the formula of the form*

$$\forall X_1 \dots \forall X_n \phi$$

where ϕ is a first-order formula and the second order quantifier prefix consists only of universal quantifiers.

Examples

- *The boolean query SAT in $SO\exists$:*

$$\Phi_{SAT} \equiv (\exists \mathbf{S})(\forall \mathbf{x})(\exists \mathbf{y}) \left((P(\mathbf{x}, \mathbf{y}) \wedge \mathbf{S}(\mathbf{y})) \vee (N(\mathbf{x}, \mathbf{y}) \wedge \neg \mathbf{S}(\mathbf{y})) \right)$$

Examples

- *The boolean query SAT in $SO\exists$:*

$$\Phi_{SAT} \equiv (\exists S)(\forall x)(\exists y) \left((P(x, y) \wedge S(y)) \vee (N(x, y) \wedge \neg S(y)) \right)$$

- *The boolean query 3-COLOR in $SO\exists$:*

$$\Phi_{3-COLOR} \equiv (\exists R^1)(\exists Y^1)(\exists B^1)(\forall x) \left[(R(x) \vee Y(x) \vee B(x)) \wedge (\forall y) \left(E(x, y) \rightarrow \neg(R(x) \wedge R(y)) \wedge \neg(Y(x) \wedge Y(y)) \wedge \neg(B(x) \wedge B(y)) \right) \right]$$

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Fagin's Theorem

Theorem (1973)

NP is equal to the set of existential, second order boolean queries.

$$NP = SO\exists$$

$SO\exists \subseteq NP$

Proof

- Let $\Phi = (\exists R_1^{r_1}) \dots (\exists R_k^{r_k}) \psi$ a second-order existential sentence.
- Let τ be the vocabulary of Φ

Our task is to build an NP machine N such that for all $\mathcal{A} \in STRUC[\tau]$,

$$(\mathcal{A} \models \Phi) \Leftrightarrow (N(\text{bin}(\mathcal{A})) \downarrow)$$

$SO\exists \subseteq NP$

Proof

- Let \mathcal{A} an input structure to N , $n = \|\mathcal{A}\|$.
- N machine non-deterministically write down a binary string representation $R_i, \forall i \in [k]$.
Check if $(\mathcal{A}, R_1, \dots, R_k) \models \psi$.
If yes, then M accepts. Else, rejects.
- N accepts \mathcal{A} iff there is some choice of relations R_i s.t. $(\mathcal{A}, R_1, \dots, R_k) \models \psi$.
- By $FO \subseteq L \subseteq P$, we can test if $(\mathcal{A}, R_1, \dots, R_k) \models \psi$ in NP .



$NP \subseteq SO\exists$

Notation

- $\vec{s} = (\vec{s}_1, \dots, \vec{s}_k)$: the numbering of tape cells, $\vec{s} \in \{0, \dots, n^k - 1\}$
- $\vec{t} = (\vec{t}_1, \dots, \vec{t}_k)$: the numbering of machine's computation time, $\vec{t} \in \{0, \dots, n^k - 1\}$
- $\Gamma = \{\gamma_0, \dots, \gamma_g\} = (Q \times \Sigma) \cup \Sigma$: a listing of the possible contents of a computation cell

$NP \subseteq SO\exists$

Proof

Our task is to find a second-order sentence $SO\exists\Phi$ such that for a nondeterministic Turing machine N ,

$$(\mathcal{A} \models \Phi) \Leftrightarrow (N(\text{bin}(\mathcal{A})) \downarrow)$$

- Let N be a nondeterministic Turing machine
- Let $n = \|\mathcal{A}\|$
- Let $k > 0$ such that N uses $n^k - 1$ time and n^k space.

$NP \subseteq SO\exists$

Proof

Let Φ a second-order sentence:

$$\Phi = (\exists C_1^{2k} \dots C_g^{2k} \Delta^k) \phi$$

where

- ϕ is a first-order formula

$NP \subseteq SO\exists$

Proof

Let Φ a second-order sentence:

$$\Phi = (\exists C_1^{2k} \dots C_g^{2k} \Delta^k) \phi$$

where

- ϕ is a first-order formula
- $C_i(\vec{s}, \vec{t})$: computation cell \vec{s} at time \vec{t} contains symbol γ_i

$NP \subseteq SO\exists$

Proof

Let Φ a second-order sentence:

$$\Phi = (\exists C_1^{2k} \dots C_g^{2k} \Delta^k) \phi$$

where

- ϕ is a first-order formula
- $C_i(\vec{s}, \vec{t})$: computation cell \vec{s} at time \vec{t} contains symbol γ_i
- $\Delta(\vec{t}) = \begin{cases} 1, & \text{if machine makes choice "1" at step } t + 1 \\ 0, & \text{otherwise} \end{cases}$

$NP \subseteq SO\exists$

Proof

We define $\phi(\vec{C}, \Delta)$ as the conjunction of four sentences,

$$\phi \equiv \alpha \wedge \beta \wedge \eta \wedge \zeta$$

where

- α : for $\vec{t} = 0$ correctly codes input $\text{bin}(\mathcal{A})$

$$\alpha \equiv \dots \wedge \left(\vec{t} = 0 = \mathbf{s}_1 = \dots = \mathbf{s}_{k-1} \wedge \mathbf{s}_k \neq 0 \wedge \mathbf{R}_1(\mathbf{s}_k) \rightarrow \mathbf{C}_1(\vec{\mathbf{s}}, \vec{\mathbf{t}}) \right)$$

$$\wedge \left(\vec{t} = 0 = \mathbf{s}_1 = \dots = \mathbf{s}_{k-1} \wedge \mathbf{s}_k \neq 0 \wedge \neg \mathbf{R}_1(\mathbf{s}_k) \rightarrow \mathbf{C}_0(\vec{\mathbf{s}}, \vec{\mathbf{t}}) \right) \wedge \dots$$

$NP \subseteq SO\exists$

Proof

- β : it is never the case that $C_i(\vec{s}, \vec{t})$ and $C_j(\vec{s}, \vec{t})$ both hold for $i \neq j$

$$\beta \equiv \bigwedge_{i,j} \beta_{ij}$$

where

$$\beta_{ij} = \neg(C_i(\vec{s}, \vec{t}) \wedge C_j(\vec{s}, \vec{t})) \text{ for } i \neq j$$

$NP \subseteq SO\exists$

Proof

- η : for all time \vec{t} , the contents of tape cell $(\vec{s}, \vec{t} + 1)$ follows from the contents of cells $(\vec{s} - 1, \vec{t})$, (\vec{s}, \vec{t}) and $(\vec{s} + 1, \vec{t})$ via the move $\Delta(\vec{t})$ of N

$$\eta \equiv \eta_0 \wedge \eta_1 \wedge \eta_2$$

where

$NP \subseteq SO\exists$ **Proof**

$$\eta_1 \equiv (\forall \vec{t}, \vec{s}) \left((\vec{t} \neq \vec{max} \wedge \vec{0} < \vec{s} < \vec{max}) \rightarrow \bigwedge_{(\alpha_{-1}, \alpha_0, \alpha_1, \delta) \xrightarrow{N} b} \left((\delta = 1 \rightarrow \left((\Delta(\vec{t}) \wedge C_{\alpha_{-1}}(\vec{s} - 1, \vec{t}) \wedge C_{\alpha_0}(\vec{s}, \vec{t}) \wedge C_{\alpha_1}(\vec{s} + 1, \vec{t})) \rightarrow C_b(\vec{s}, \vec{t} + 1) \right)) \wedge \left((\delta = 0 \rightarrow \left((\neg \Delta(\vec{t}) \wedge C_{\alpha_{-1}}(\vec{s} - 1, \vec{t}) \wedge C_{\alpha_0}(\vec{s}, \vec{t}) \wedge C_{\alpha_1}(\vec{s} + 1, \vec{t})) \rightarrow C_b(\vec{s}, \vec{t} + 1) \right) \right) \right) \right) \right)$$

$NP \subseteq SO\exists$ **Proof**

$$\eta_1 \equiv (\forall \vec{t}, \vec{s}) \left((\vec{t} \neq \vec{max} \wedge \vec{0} < \vec{s} < \vec{max}) \rightarrow \bigwedge_{(\alpha_{-1}, \alpha_0, \alpha_1, \delta) \xrightarrow{N} b} \left((\delta = 1 \rightarrow \left((\Delta(\vec{t}) \wedge C_{\alpha_{-1}}(\vec{s} - 1, \vec{t}) \wedge C_{\alpha_0}(\vec{s}, \vec{t}) \wedge C_{\alpha_1}(\vec{s} + 1, \vec{t})) \rightarrow C_b(\vec{s}, \vec{t} + 1) \right)) \wedge \left((\delta = 0 \rightarrow \left((\neg \Delta(\vec{t}) \wedge C_{\alpha_{-1}}(\vec{s} - 1, \vec{t}) \wedge C_{\alpha_0}(\vec{s}, \vec{t}) \wedge C_{\alpha_1}(\vec{s} + 1, \vec{t})) \rightarrow C_b(\vec{s}, \vec{t} + 1) \right)) \right) \right) \right)$$

η_0 and η_2 are the same with η_1 for $\vec{s} = \vec{0}$ and $\vec{s} = \vec{max}$ respectively

$NP \subseteq SO\exists$ **Proof**

- ζ : for $\vec{t} = n^k - 1$, machine includes the accept state
 - ↳ N accepts it, clears its tape, moves all the way to left and enters a unique accept state q_l
 - ↳ If $\gamma_l = (q_l, 0) \in \Gamma$, then

$$\zeta \equiv C_l(\vec{0}, \vec{m}\vec{x})$$



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NP-Complete Problems

Corollary (Cook)

SAT is NP-complete via first-order reductions.

NP-Complete Problems

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SAT is NP-complete via first-order reductions.

Proof

- *Let $B \in NP$ be any boolean query and \mathcal{A} be any input structure with $n = \|\mathcal{A}\|$.*
- *By Fagin's theorem, $B = MOD[\Phi]$ where $\Phi = (\exists S_1^{\alpha_1} \dots \exists S_g^{\alpha_g})(\forall x_1 \dots \forall x_t)\psi(\vec{x})$ with ψ quantifier-free and we assume that $\psi(\vec{x}) = \bigwedge_{j=1}^r C_j(\vec{x})$*

$$\mathcal{A} \in B \Leftrightarrow \mathcal{A} \models \Phi$$

NP-Complete Problems

Proof

Define the boolean formula $\gamma(\mathcal{A})$ as follows:

- *Boolean variables:*

$$S_i(\mathbf{e}_1, \dots, \mathbf{e}_{\alpha_i}) \text{ and } D(\mathbf{e}_1, \dots, \mathbf{e}_k),$$

for $i = \{1, \dots, g\}$ and $\mathbf{e}_1, \dots, \mathbf{e}_{\alpha_i} \in |\mathcal{A}|$

- *Clauses:*

$$C_j(\vec{\mathbf{e}}), j = 1, \dots, r$$

as $\vec{\mathbf{e}}$ ranges over all t -tuples from $|\mathcal{A}|$.

In each $C_j(\vec{\mathbf{e}})$, there may be some occurrences of numeric or input predicates: $\gamma(\vec{\mathbf{e}})$. Replacing each $\gamma(\vec{\mathbf{e}})$ by its truth value in \mathcal{A} .

NP-Complete Problems

Proof

It is clear from the construction that

$$\mathcal{A} \in B \iff \mathcal{A} \models \Phi \iff \gamma(\mathcal{A}) \in \mathbf{SAT}$$



NP-Complete Problems

Corollary

3-SAT is NP-complete via first-order reductions.

NP-Complete Problems

Corollary

3-SAT is NP-complete via first-order reductions.

Proof

We show that $SAT \leq_{fo} 3\text{-SAT}$.

- Let $\mathcal{A} \in STRUCT[\langle P^2, n^2 \rangle]$ be an instance of SAT with $n = \|\mathcal{A}\|$.*
- Each clause c of \mathcal{A} is replaced by $2n$ clauses as follows:*

$$c' \equiv ([x_1]^c \vee d_1) \wedge (\overline{d_1} \vee [x_2]^c \vee d_2) \wedge (\overline{d_2} \vee [x_3]^c \vee d_3) \wedge \dots \\ \wedge (\overline{d_n} \vee [x_1]^c \vee d_{n+1}) \wedge (\overline{d_{n+1}} \vee [x_2]^c \vee d_{n+2}) \wedge \dots \wedge (\overline{d_{2n-1}} \vee [x_n]^c)$$

NP-Complete Problems

Proof

where

- x_i 's are the instance literals
- d_i 's are new variables
- $[l]^c$ means the literal l if it occurs in c and false otherwise

$$c \in \text{SAT} \Leftrightarrow c' \in \text{SAT}$$

and c' is definable in a first order way from c .



NP-Complete Problems

Corollary

3-COLOR is NP-complete via first-order reductions.

NP-Complete Problems

Corollary

3-COLOR is NP-complete via first-order reductions.

Proof

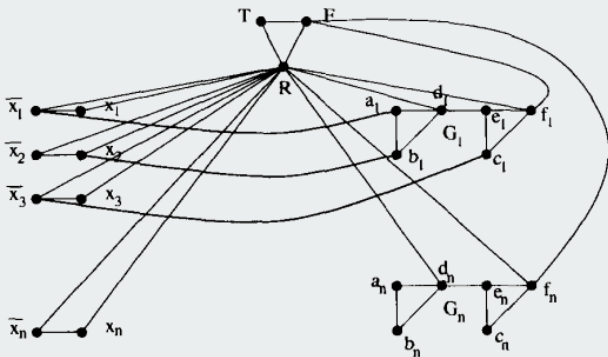
We show that $3\text{-SAT} \leq_{fo} 3\text{-COLOR}$.

- *Let \mathcal{A} be an instance of 3-SAT with $n = \|\mathcal{A}\|$.*
- *We construct graph $f(\mathcal{A})$ such that*

$$f(\mathcal{A}) \text{ 3-colorable} \Leftrightarrow \mathcal{A} \in 3\text{-SAT}$$




NP-Complete Problems

Proof



Thanks!

References

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